Four Flavors of Entailment

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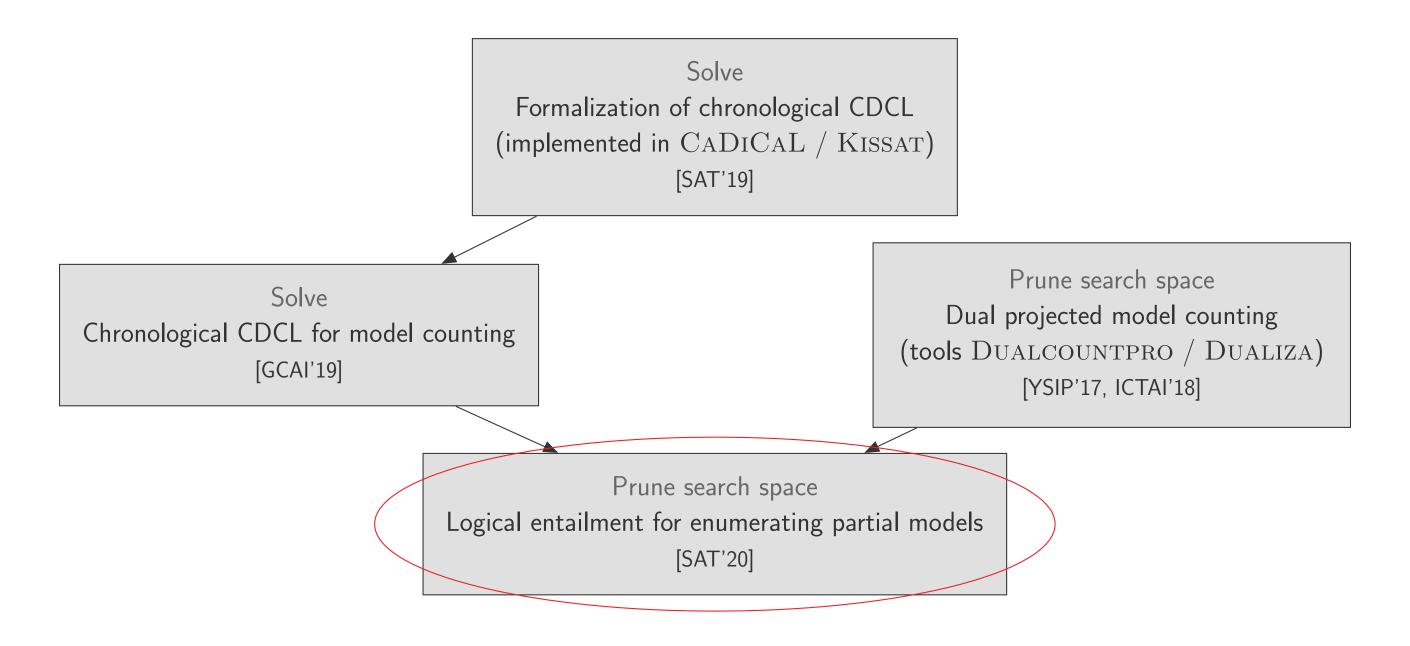


² Department of Information Engineering and Computer Science



LogiCS Research Seminar

16 March 2021



Outline

Motivation and Design Choices

Logical Entailment Condition Under Projection

Towards Four Flavors of Logical Entailment

Algorithm and Calculus

A Closer Look at the Calculus

Conclusion

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Motivation

Model Enumeration has Various Applications

- Iazy Satisfiability Modulo Theories (Sebastiani, JSAT, 2007)
- predicate abstraction (Lahiri, Nieuwenhuis and Oliveras, CAV'06)
- software product line engineering (Galindo et al., SPLC'16)
- model checking (Biere et al., TACAS'99; McMillan, CAV'02; Strichman, CAV'00)
- preimage computation (Li, Hsiao and Sheng, DATE'04; Sheng and Hsiao, DATE'03)
- weighted model counting (Sang, Beame and Kautz, AAAI'05; Chavira and Darwiche, Artif. Intell., 2008)
- weighted model integration (Morettin, Passerini and Sebastiani, IJCAI'17 and Artif. Intell., 2019)

Motivation

Model Enumeration has Various Applications

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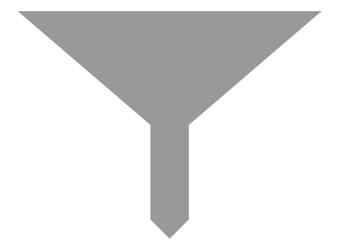
no repetitions, please!

We need...

- ... short (partial) models
 - model shrinking
 (Tibebu and Fey, DDECS'18)
 - dual reasoning (M and Biere, ICTAI'18)
 - logical entailment (Sebastiani, arXiv.org, 2020)

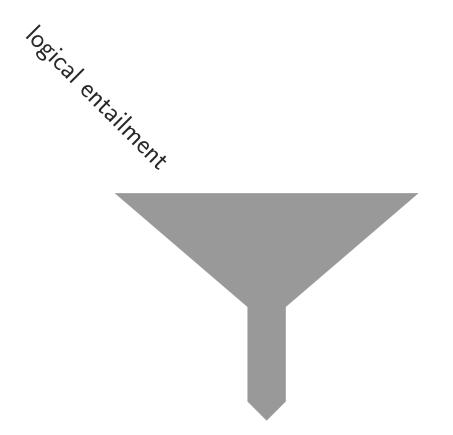
Example
$$F = (x \land y) \lor (x \land \neg y)$$

 $F|_x = y \lor \neg y \neq 1$
 $F|_{xy} = F|_{x\neg y} = 1 \implies x \models F$



We need...

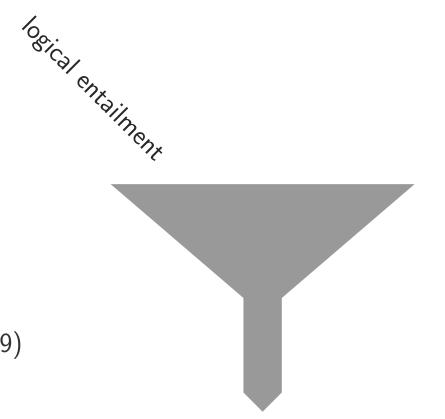
... short (partial) models



We need...

... short (partial) models

- ... pairwise disjoint models
 - add the negated models as blocking clauses
 - variant of conflict analysis
 (Toda and Soh, ACM J. Exp. Algorithmics, 2016)
 - chronological CDCL (Nadel and Ryvchin, SAT'18; M and Biere, SAT'19)

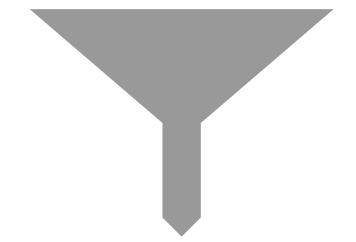


We need...

... short (partial) models

... pairwise disjoint models



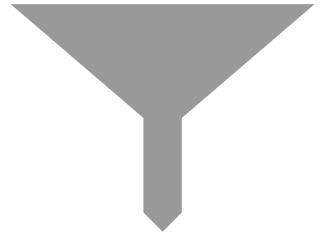


We need...

- ...short (partial) models
- ... pairwise disjoint models
- ... projection
 - $F(X,Y) \ \, \text{where} \ \, X\cap Y=\emptyset$
 - X relevant variables
 - Y irrelevant variables

 $\exists Y \, [\, F(X,Y) \,] \qquad \text{project} \, \, F(X,Y) \, \, \text{onto} \, \, X$



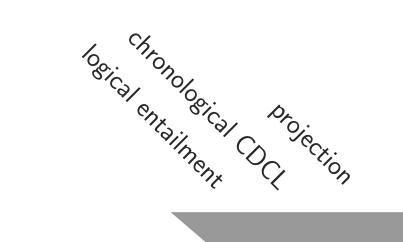


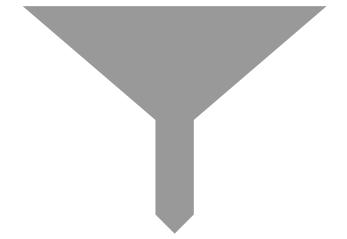
We need...

... short (partial) models

... pairwise disjoint models

... projection



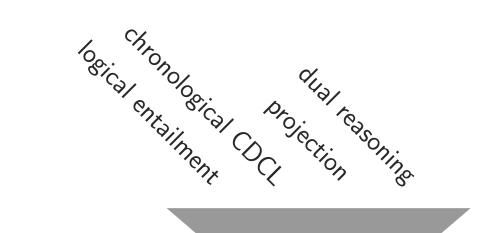


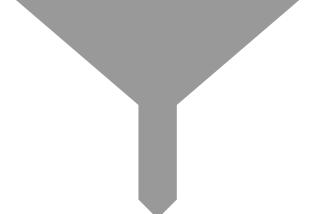
We need...

... short (partial) models

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We need...

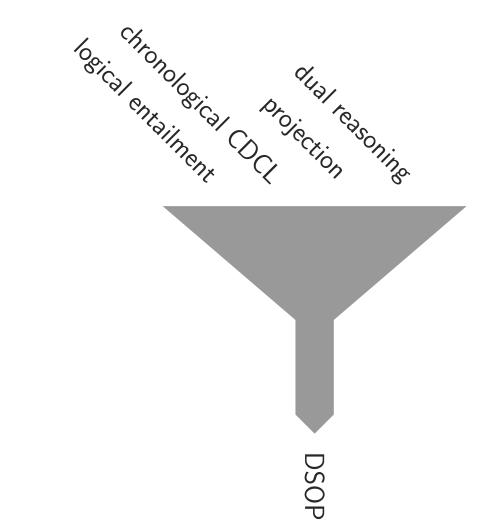
... short (partial) models

... pairwise disjoint models

... projection

We get...

. Disjoint Sum-of-Products (DSOP) . (well known in circuit design



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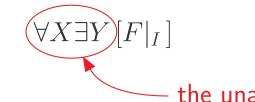
Conclusion

 $\begin{array}{lll} \mbox{Given:} & F(X,Y) & \mbox{formula over a set of relevant variables } X \mbox{ and a set of irrelevant variables } Y \\ & I & \mbox{trail over variables in } X \cup Y \end{array}$

Entailment under projection onto X: $\forall X \exists Y [F|_I]$

Given: F(X,Y) formula over a set of relevant variables X and a set of irrelevant variables YI trail over variables in $X \cup Y$

Entailment under projection onto X:



- the unassigned variables are quantified

Given: F(X,Y) formula over a set of relevant variables X and a set of irrelevant variables YI trail over variables in $X \cup Y$

Entailment under projection onto X: $\forall X \exists Y [F|_I]$

Example:
$$F(X,Y) = x_1(x_2 \leftrightarrow y_2)$$
 $X = \{x_1, x_2\}$ $Y = \{y_2\}$
 $F|_{x_1} = (x_2 \leftrightarrow y_2)$
 $F|_{x_1x_2} = (1 \leftrightarrow y_2)$ and $F|_{x_1x_2y_2} = 1$
 $F|_{x_1\overline{x_2}} = (0 \leftrightarrow y_2)$ and $F|_{x_1\overline{x_2}\overline{y_2}} = 1$
 $\implies x_1 \models F$

Given: F(X,Y) formula over a set of relevant variables X and a set of irrelevant variables Y I trail over variables in $X \cup Y$

Entailment under projection onto X: $\forall X \exists Y [F|_I]$

Example: $F(X,Y) = x_1(x_2 \leftrightarrow y_2)$ $X = \{x_1, x_2\}$ $Y = \{y_2\}$ $F|_{x_1} = (x_2 \leftrightarrow y_2)$ $F|_{x_1x_2} = (1 \leftrightarrow y_2)$ and $F|_{x_1x_2y_2} = 1$ $F|_{x_1\overline{x_2}} = (0 \leftrightarrow y_2)$ and $F|_{x_1\overline{x_2}\overline{y_2}} = 1$ $\Rightarrow x_1 \models F$ $Y = \{y_2\}$ Does for each J_X exist *one* J_Y such that $F|_{I'} = 1$ where $I' = I \cup J_X \cup J_Y$?

Given: F(X,Y) formula over a set of relevant variables X and a set of irrelevant variables Y trail over variables in $X \cup Y$ Τ

Entailment under projection onto $X: \forall X \exists Y [F]_I$

Example:
$$F(X,Y) = x_1(x_2 \leftrightarrow y_2)$$
 $X = \{x_1, x_2\}$ $Y = \{y_2\}$ $F|_{x_1} = (x_2 \leftrightarrow y_2)$ Does for each J_X exist one J_Y such that $F|_{x_1x_2} = (1 \leftrightarrow y_2)$ and $F|_{x_1x_2y_2} = 1$ $F|_{I'} = 1$ where $I' = I \cup J_X \cup J_Y$? $F|_{x_1\overline{x_2}} = (0 \leftrightarrow y_2)$ and $F|_{x_1\overline{x_2}\overline{y_2}} = 1$ $QBF(\varphi) = 1$ where $\varphi = \forall X \exists Y [F|_I] = 1$? $\Rightarrow x_1 \models F$ But this check is expensive \mathfrak{S}

this check is expensive \bigcirc

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Motivation and Design Choices

Logical Entailment Condition Under Projection

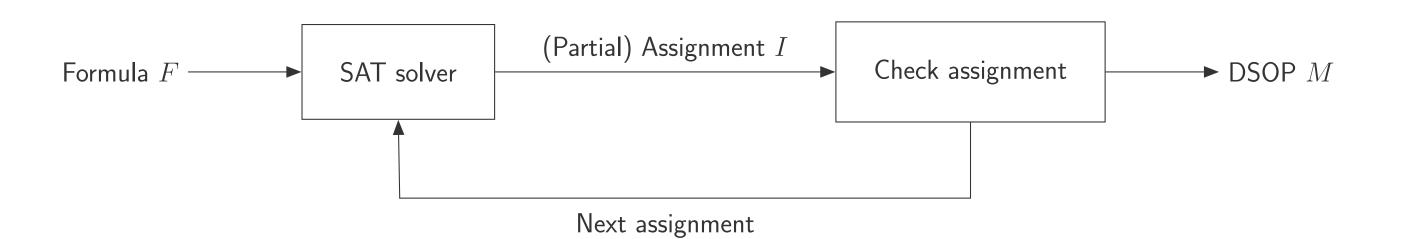
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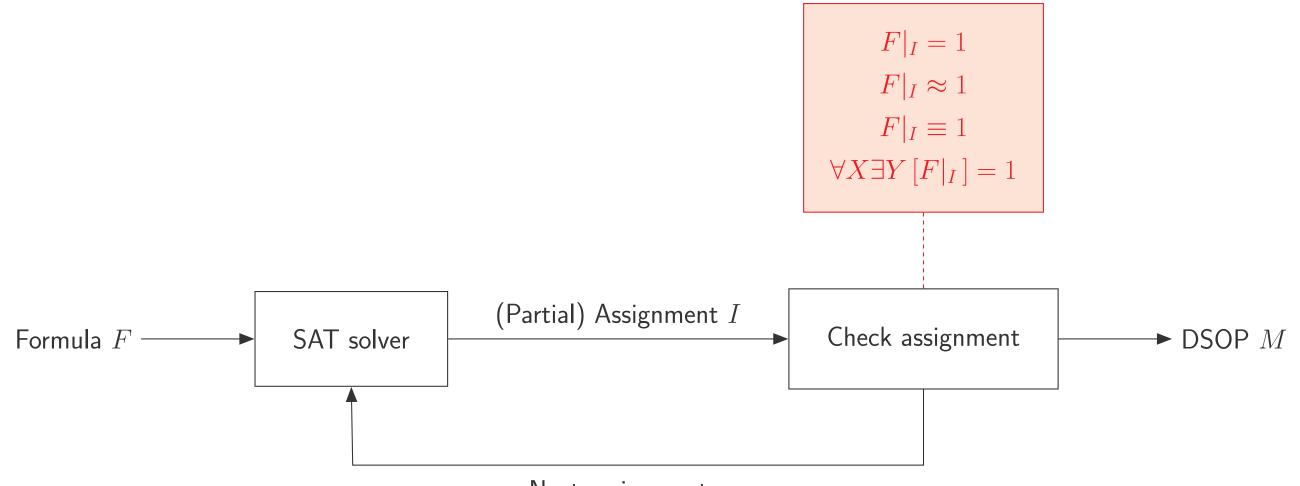
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Main Idea



Our Contribution



Next assignment

1) $F|_I = 1$ (syntactic check)

$$F = (x_1 \lor y \lor x_2) \qquad X = \{x_1, x_2\} \qquad Y = \{y\}$$
$$I = x_1: \qquad F|_I = 1 \implies I \models F$$

1) $F|_I = 1$ (syntactic check)

2) $F|_I \approx 1$ (incomplete check in **P**)

$$F = x_1 y \lor \overline{y} x_2 \qquad X = \{x_1, x_2\} \qquad Y = \{y\}$$

$$I = x_1 x_2: \qquad F|_I = y \lor \overline{y} \neq 1 \quad \text{but is valid}$$

$$I = x_1 x_2 \overline{y}: \qquad 0 \in BCP(\neg F, I) \implies x_1 x_2 \models F$$

- 1) $F|_I = 1$ (syntactic check)
- 2) $F|_I \approx 1$ (incomplete check in **P**)
- 3) $F|_I \equiv 1$ (semantic check in **coNP**)

$$F = x_1(\overline{x_2} \, \overline{y} \lor \overline{x_2} y \lor x_2 \overline{y} \lor x_2 y) \qquad X = \{x_1, x_2\} \qquad Y = \{y\}$$

$$I = x_1: \qquad I(F) = \overline{x_2} \, \overline{y} \lor \overline{x_2} y \lor x_2 \overline{y} \lor x_2 y \neq 1 \qquad \text{but is valid}$$

$$P = \mathsf{CNF}(F)$$

$$N = \mathsf{CNF}(\neg F):$$

$$P|_I \text{ and } N|_I \text{ are non-constant and contain no units}$$

 $N|_{I} = (x_{2} \lor y)(x_{2} \lor \overline{y})(\overline{x_{2}} \lor y)(\overline{x_{2}} \lor \overline{y}): \quad SAT(N \land I) = 0 \quad \Longrightarrow \quad I \models F$

- 1) $F|_I = 1$ (syntactic check)
- 2) $F|_I \approx 1$ (incomplete check in **P**)
- 3) $F|_I \equiv 1$ (semantic check in coNP)
- 4) $\forall X \exists Y [F|_I] = 1$ (check in Π_2^P)

 $F = x_1(x_2 \leftrightarrow y_2)$ $X = \{x_1, x_2\}$ $Y = \{y_2\}$

 $P = \mathsf{CNF}(F)$ and $N = \mathsf{CNF}(\neg F)$:

 $P = (x_1)(s_1 \lor s_2)(\overline{s_1} \lor x_2)(\overline{s_1} \lor y_2)(\overline{s_2} \lor \overline{x_2})(\overline{s_2} \lor \overline{y_2}) \quad \text{where} \quad S = \{s_1, s_2\}$ $N = (\overline{x_1} \lor t_1 \lor t_2)(\overline{t_1} \lor x_2)(\overline{t_1} \lor \overline{y_2})(\overline{t_2} \lor \overline{x_2})(\overline{t_2} \lor y_2) \quad \text{where} \quad T = \{t_1, t_2\}$ $I = x_1: \qquad P|_I \text{ and } N|_I \text{ are non-constant and contain no units}$ $I = x_1 x_2^d \overline{t_2} t_1 \overline{y_2}: \qquad N|_I = 1$ $\varphi = \forall X \exists Y [x_2 y_2 \lor \overline{x_2} \overline{y_2}]: \qquad QBF(\varphi) = 1 \implies x_1 \models F$

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Algorithm

Input: formula F(X, Y) over variables $X \cup Y$ such that $X \cap Y = \emptyset$, trail I, decision level function δ **Output:** M DSOP representation of F projected onto X

```
Count(F)
 1 I := \varepsilon; \delta := \infty; M := 0
 2 forever do
         C := \mathsf{PropagateUnits}(F, I, \delta)
 3
         if C \neq 0 then
 4
               c := \delta(C)
 5
               if c = 0 then return M
 6
               AnalyzeConflict (F, I, C, c)
 7
          else if all variables in X \cup Y are assigned then
 8
               if V(\operatorname{decs}(I)) \cap X = \emptyset then return M \vee \pi(I, X)
 9
               M := M \vee \pi(I, X)
10
               b := \delta(\mathsf{decs}(\pi(I, X)))
11
               Backtrack (I, b-1)
12
```

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                M := M \vee \pi(I, X)
10
               b := \delta(\mathsf{decs}(\pi(I, X)))
11
                \mathsf{Backtrack}(I, b-1)
12
          else if Entails (I, F) then
13
                if V(\operatorname{decs}(I)) \cap X = \emptyset then return M \vee \pi(I, X)
14
               M := M \lor \pi(I, X)
15
               b := \delta(\mathsf{decs}(\pi(I, X)))
16
                Backtrack (I, b-1)
17
          else Decide (I, \delta)
18
```

Calculus

EndTrue:	$(F, I, M, \delta) \sim_{EndTrue} M \lor m \text{ if } V(decs(I)) \cap X = \emptyset \text{ and}$ $m \stackrel{\text{def}}{=} \pi(I, X) \text{ and } \forall X \exists Y [F _I] = 1$
EndFalse:	$(F, I, M, \delta) \sim_{EndFalse} M$ if exists $C \in F$ and $C _I = 0$ and $\delta(C) = 0$
Unit:	$(F, I, M, \delta) \sim_{\text{Unit}} (F, I\ell, M, \delta[\ell \mapsto a]) \text{ if } F _I \neq 0 \text{ and}$ exists $C \in F$ with $\{\ell\} = C _I$ and $a \stackrel{\text{def}}{=} \delta(C \setminus \{\ell\})$
BackTrue	$ (F, I, M, \delta) \sim_{BackTrue} (F, UK\ell, M \lor m, \delta[L \mapsto \infty][\ell \mapsto b]) \text{ if } UV \stackrel{\text{def}}{=} I \text{ and } D \stackrel{\text{def}}{=} \overline{\pi(decs(I), X)} \text{ and } b + 1 \stackrel{\text{def}}{=} \delta(D) \leqslant \delta(I) \text{ and } \ell \in D \text{ and } b = \delta(D \setminus \{\ell\}) = \delta(U) \text{ and } m \stackrel{\text{def}}{=} \pi(I, X) \text{ and } K \stackrel{\text{def}}{=} V_{\leqslant b} \text{ and } L \stackrel{\text{def}}{=} V_{>b} \text{ and } \forall X \exists Y[F _I] = 1 $
BackFalse	$\begin{array}{l} :: (F, I, M, \delta) \sim_{BackFalse} (F, UK\ell, M, \delta[L \mapsto \infty][\ell \mapsto j]) \text{if} \\ \text{exists } C \in F \ \text{and exists } D \ \text{with } UV \stackrel{\text{def}}{=} I \ \text{and } C _I = 0 \ \text{and} \\ c \stackrel{\text{def}}{=} \delta(C) = \delta(D) > 0 \ \text{such that } \ell \in D \ \text{and } \bar{\ell} \in decs(I) \ \text{and} \\ \bar{\ell} _V = 0 \ \text{and} \ F \wedge \overline{M} \models D \ \text{and} \ j \stackrel{\text{def}}{=} \delta(D \setminus \{\ell\}) \ \text{and} \\ b \stackrel{\text{def}}{=} \delta(U) = c - 1 \ \text{and} \ K \stackrel{\text{def}}{=} V_{\leqslant b} \ \text{and} \ L \stackrel{\text{def}}{=} V_{>b} \end{array}$
DecideX:	$(F, I, M, \delta) \sim_{DecideX} (F, I\ell^d, M, \delta[\ell \mapsto d]) \text{ if } F _I \neq 0 \text{ and}$ units $(F _I) = \emptyset$ and $\delta(\ell) = \infty$ and $d \stackrel{\text{def}}{=} \delta(I) + 1$ and $V(\ell) \in X$
DecideY:	$(F, I, M, \delta) \sim_{DecideY} (F, I\ell^d, M, \delta[\ell \mapsto d]) \text{ if } F _I \neq 0 \text{ and}$ units $(F _I) = \emptyset$ and $\delta(\ell) = \infty$ and $d \stackrel{\text{def}}{=} \delta(I) + 1$ and $V(\ell) \in Y$ and $X - I = \emptyset$

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Unit Propagation

Idea: Assign the propagated unit literal the decision level of its reason clause

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Unit:

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Unit: (F, I, M, δ)

Idea: Assign the propagated unit literal the decision level of its reason clause

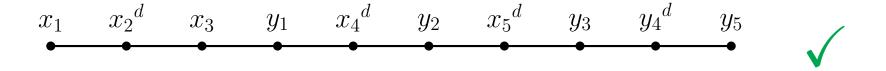
 $\mathsf{Unit:}\ (F,\ I,\ M,\ \delta) \rightsquigarrow_{\mathsf{Unit}}\ (F,\ I\ell,\ M,\ \delta[\ell \mapsto a]) \quad \mathsf{if} \quad F|_I \neq 0 \quad \mathsf{and} \quad \mathsf{exists}\ C \in F \quad \mathsf{with} \quad \{\ell\} = C|_I \quad \mathsf{and} \quad a \stackrel{\mathsf{\tiny def}}{=} \delta(C \setminus \{\ell\})$

Idea: Assign the propagated unit literal the decision level of its reason clause

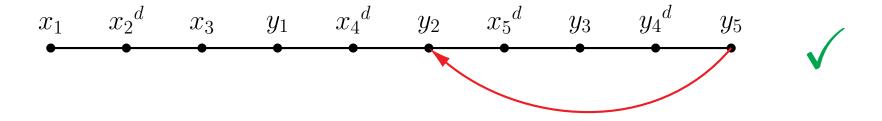
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Given: Formula F(X, Y) over relevant variables X and irrelevant variables Y

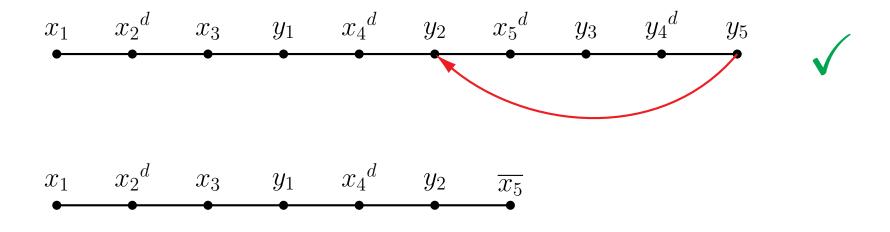
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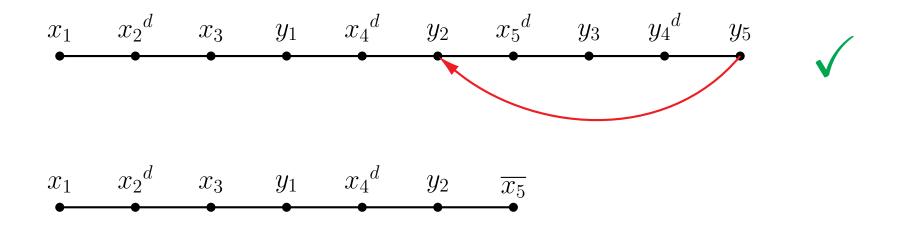


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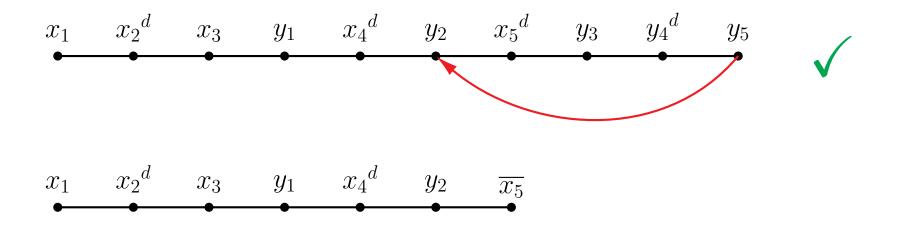
Idea: Flip the last relevant decision literal



BackTrue:

Given: Formula F(X, Y) over relevant variables X and irrelevant variables Y

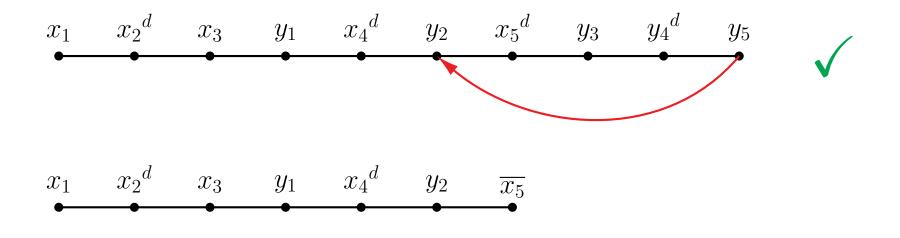
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BackTrue: (F, I, M, δ)

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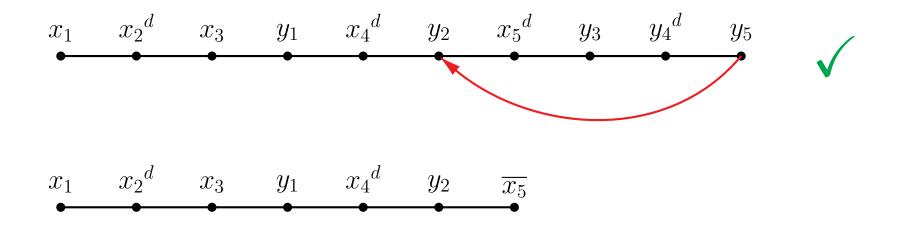


BackTrue: (F, I, M, δ)

if $\forall X \exists Y [F|_I] = 1$

Given: Formula F(X, Y) over relevant variables X and irrelevant variables Y

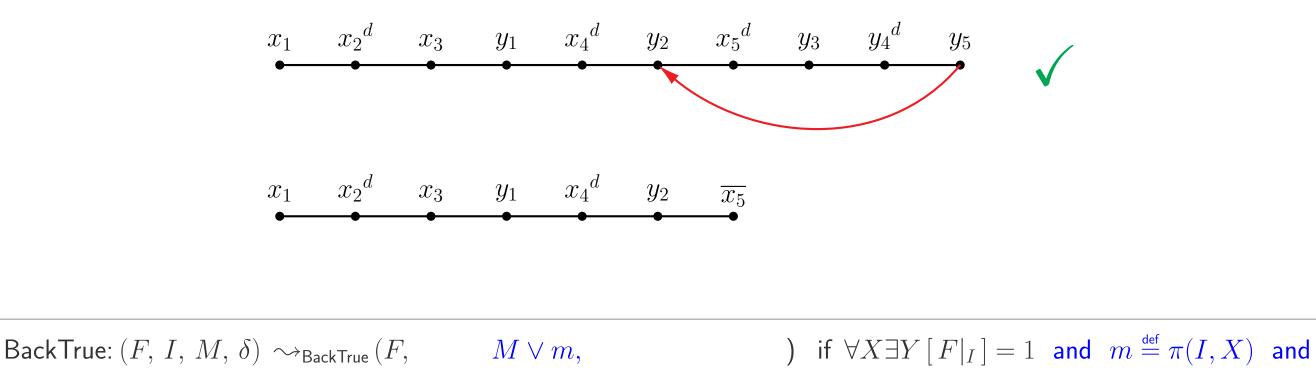
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BackTrue: $(F, I, M, \delta) \sim_{\mathsf{BackTrue}} (F,$

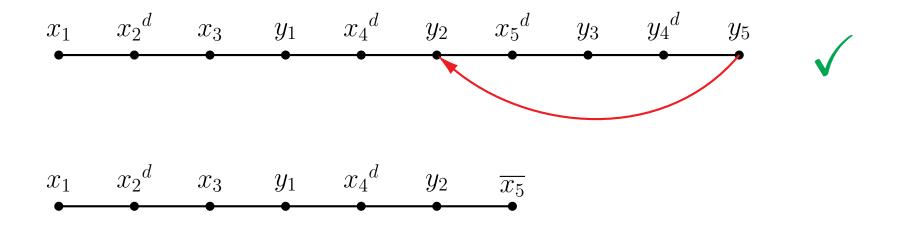
) if $\forall X \exists Y [F|_I] = 1$

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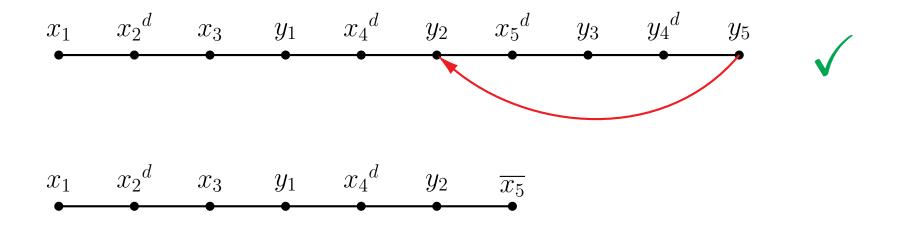
Idea: Flip the last relevant decision literal



BackTrue: $(F, I, M, \delta) \rightsquigarrow_{\mathsf{BackTrue}} (F, UK\ell, M + m,)$ if $\forall X \exists Y [F|_I] = 1$ and $m \stackrel{\text{def}}{=} \pi(I, X)$ and $D \stackrel{\text{def}}{=} \overline{\pi(\mathsf{decs}(I), X)}$ and $\ell \in D$ and $UV \stackrel{\text{def}}{=} I$ and $K \stackrel{\text{def}}{=} V_{\leqslant b}$ and

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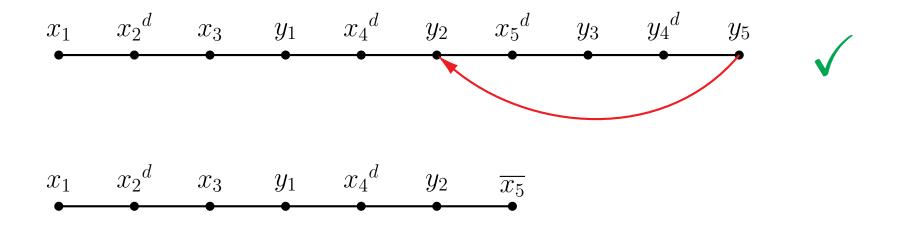
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 $\begin{array}{l} \mathsf{BackTrue:} \left(F,\,I,\,M,\,\delta\right) \rightsquigarrow_{\mathsf{BackTrue}} \left(F,\,UK\ell,\,M+m,\,\delta[L\mapsto\infty][\ell\mapsto b]\right) \ \text{if} \ \forall X \exists Y \left[\,F|_{I}\,\right] = 1 \ \text{and} \ m \stackrel{\mathsf{def}}{=} \pi(I,X) \ \text{and} \ D \stackrel{\mathsf{def}}{=} \overline{\pi(\mathsf{decs}(I),X)} \ \text{and} \ \ell \in D \ \text{and} \ UV \stackrel{\mathsf{def}}{=} I \ \text{and} \ K \stackrel{\mathsf{def}}{=} V_{\leqslant b} \ \text{and} \ b = \delta(D \setminus \{\ell\}) = \delta(U) \ \text{and} \ b + 1 \stackrel{\mathsf{def}}{=} \delta(D) \leqslant \delta(I) \ \text{and} \ L \stackrel{\mathsf{def}}{=} V_{>b} \end{array}$

Given: Formula F(X, Y) over relevant variables X and irrelevant variables Y

Idea: Flip the last relevant decision literal



 $\begin{array}{l} \mathsf{BackTrue:} \left(F,\,I,\,M,\,\delta\right) \rightsquigarrow_{\mathsf{BackTrue}} \left(F,\,UK\ell,\,M+m,\,\delta[L\mapsto\infty][\ell\mapsto b]\right) \ \text{if } \forall X \exists Y \left[\,F|_{I}\,\right] = 1 \ \text{and} \ m \stackrel{\text{def}}{=} \pi(I,X) \ \text{and} \ D \stackrel{\text{def}}{=} \overline{\pi(\mathsf{decs}(I),X)} \ \text{and} \ \ell \in D \ \text{and} \ UV \stackrel{\text{def}}{=} I \ \text{and} \ K \stackrel{\text{def}}{=} V_{\leqslant b} \ \text{and} \ b = \delta(D \setminus \{\ell\}) = \delta(U) \ \text{and} \ b + 1 \stackrel{\text{def}}{=} \delta(D) \leqslant \delta(I) \ \text{and} \ L \stackrel{\text{def}}{=} V_{>b} \end{array}$

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Motivation and Design Choices

Logical Entailment Condition Under Projection

Towards Four Flavors of Logical Entailment

Algorithm and Calculus

A Closer Look at the Calculus

Conclusion

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Our Contribution

Method for computing partial assignments entailing the formula on the fly

- Inspired by the interaction of theory and SAT solvers in SMT
- Combines dual reasoning and chronological CDCL
- Algorithm (in the paper)
- Formalization (in the paper)

Entailment test in four flavors of increasing strength

- $F|_I = 1$ (syntactic check)
- $F|_I \approx 1$ (incomplete check in **P**)
- $F|_I \equiv 1$ (semantic check in **coNP**)
- $\forall X \exists Y [F|_I] = 1$ (check in Π_2^P)

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Further Research

- Implement and validate our method
- Target weighted model integration and model counting with or without projection
- Investigate methods concerning the implementation of QBF oracles
 - Dependency schemes (Samer and Szeider, JAR, 2009)
 - Incremental QBF (Lonsing and Egly, CP'14)
- Combine with decomposition-based approaches and generate d-DNNF